

---

# Fraunhofer Institute of Optronics, System Technologies and Image Exploitation IOSB

---

## Compressive sensing imaging through atmospheric turbulence

Gabriela Paunescu, Daniel Wegner, Peter Lutzmann, Endre Repasi  
Salamanca, 6 - 7 May 2019



Karlsruhe



Ettlingen



Ilmenau



Lemgo

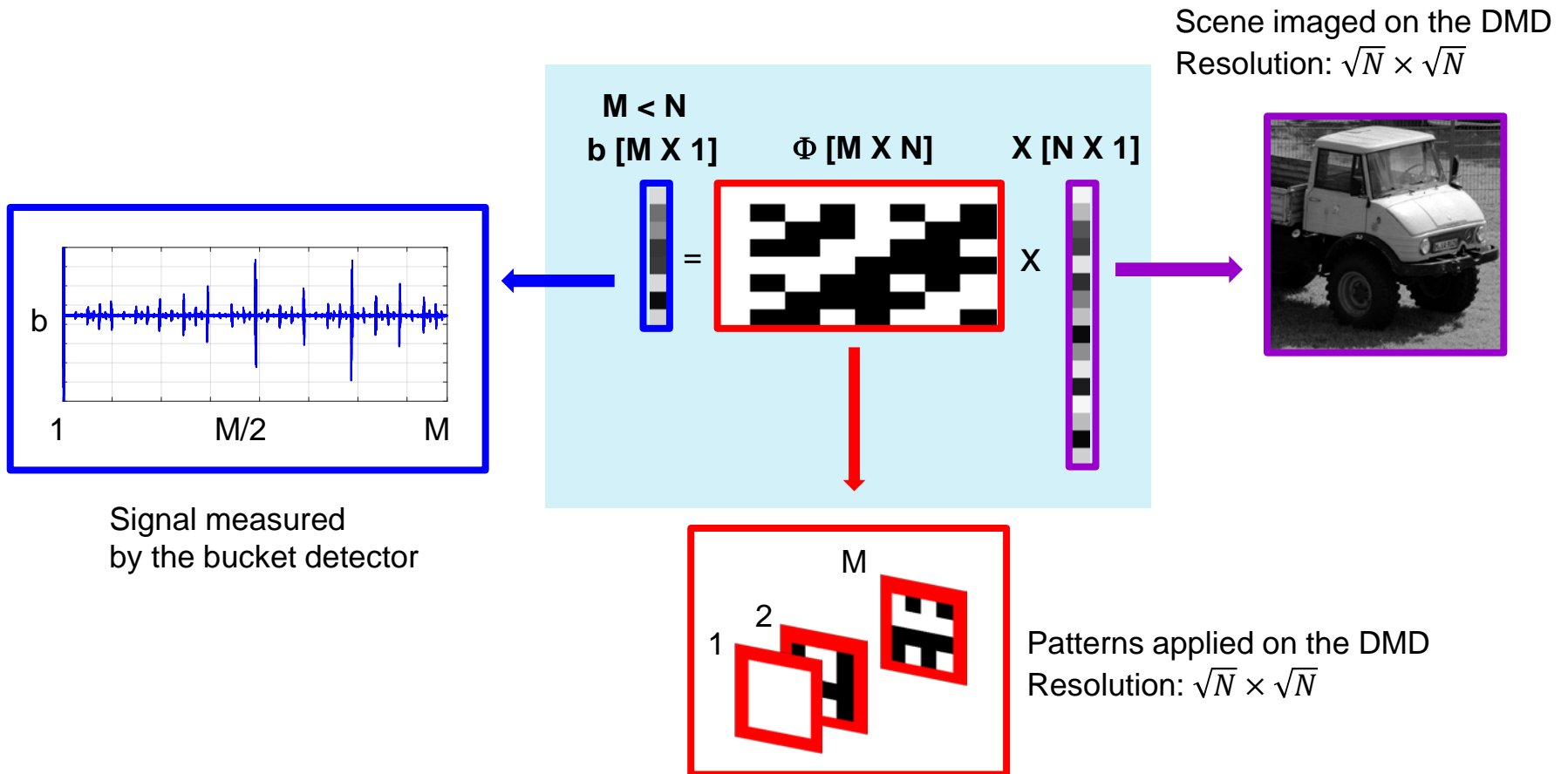


Görlitz

# Motivation

- The technique allows the reconstruction of a high resolution image using data acquired with a lower resolution sensor
  - Number of acquisitions  $<$  image resolution
- 
- To expand further spectral ranges for applications as e.g. gated viewing and 3D imaging sensors
  - To surrogate expensive 2D detector arrays
- 
- FPA-images through turbulence degrades due to intensity fluctuation, distortion, and blur, notably for long-range applications
  - The sensitivity of CS imaging techniques to atmospheric turbulence has not been rigorously investigated so far
  - To date, no comparative study on the turbulence influence on both types of systems is available

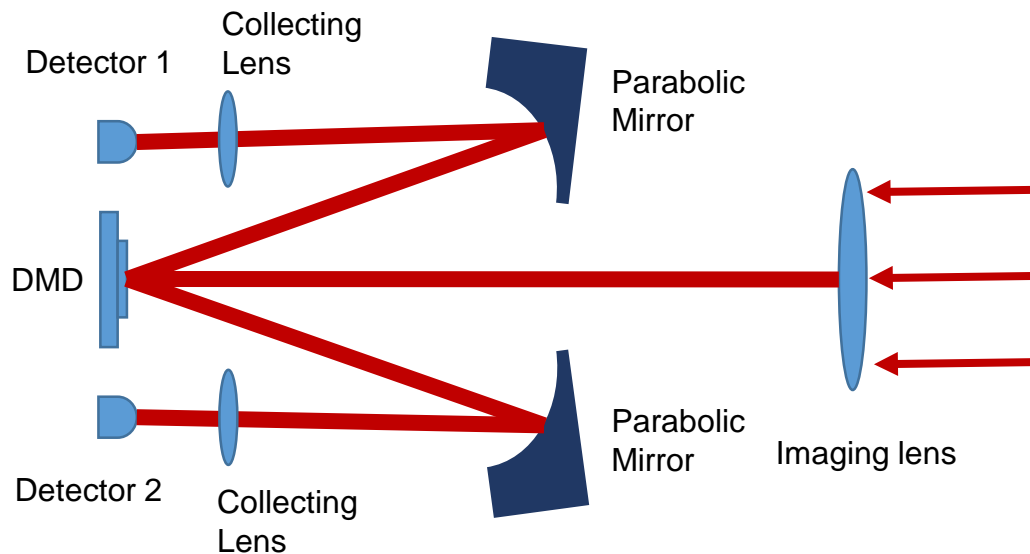
# Compressed sensing measurement



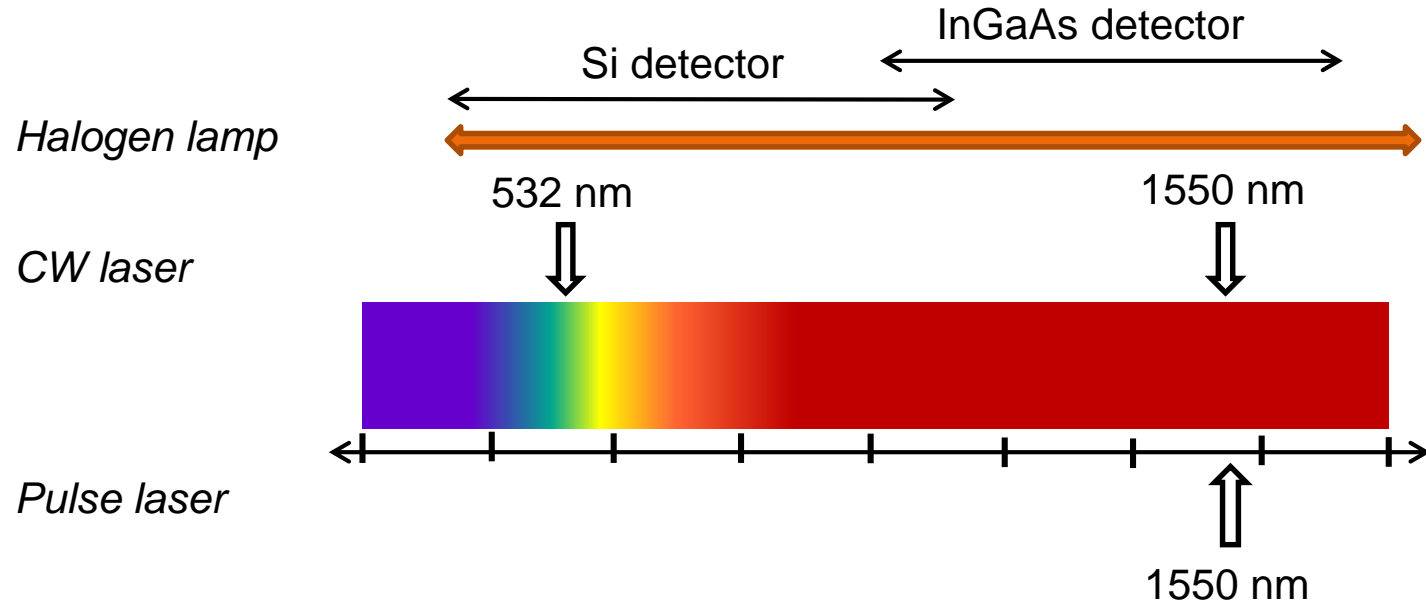
# Experimental setup

Simultaneously acquisition of complementary patterns modulated signal:

- *Sum of the two signals used for intensity variation correction*
- *Improvement of image reconstruction*
- *Background light correction*
- *Multispectral imaging e.g. VIS and SWIR*



# Illumination sources and detectors



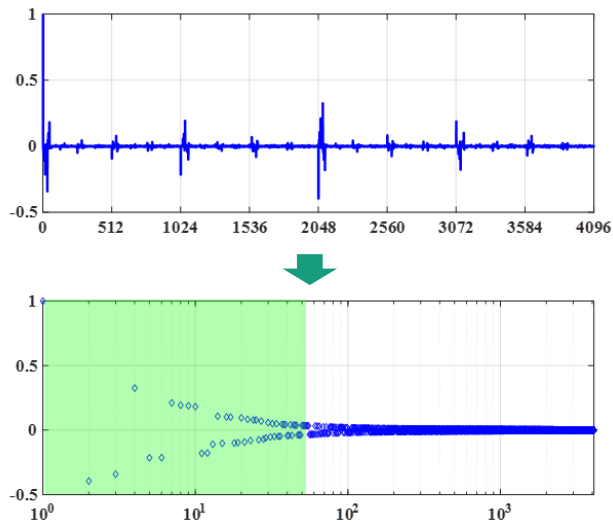
Light source	Detector	Overlap spectral range
Halogen lamp	Si photodiode	VIS: 350 – 1100 nm
Halogen lamp	InGaAs photodiode	SWIR: 800 – 1700 nm
CW laser	Si photodiode	VIS: 532 nm
CW laser	InGaAs photodiode	SWIR: 1550 nm
Pulse laser	InGaAs photodiode	SWIR: 1550 nm

# Pattern selection

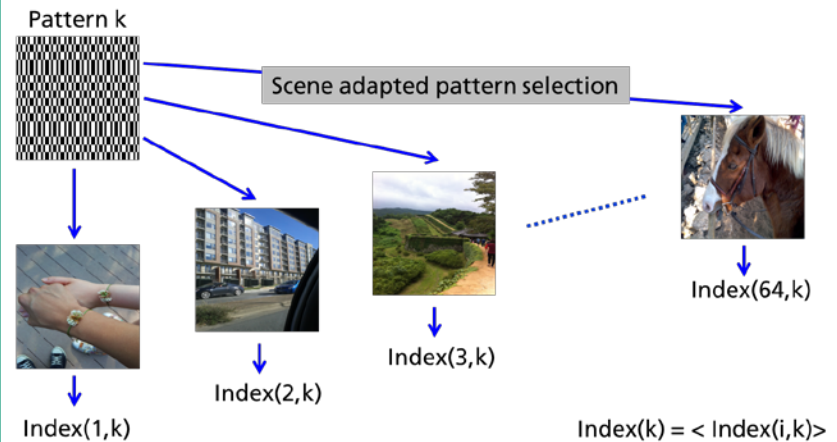
M patterns based on Hadamard matrix are selected using different methods:

- A: Sequence ordered patterns
- B: Scene adapted pattern selection
- C: Image collection relevant patterns
- D: Number of blocks ordered patterns

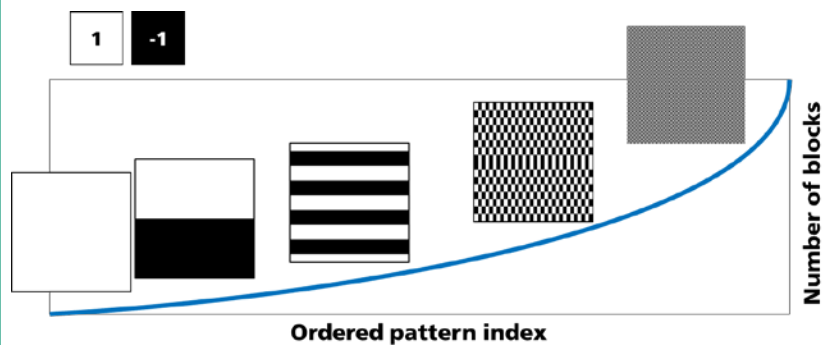
## B: Scene adapted pattern selection



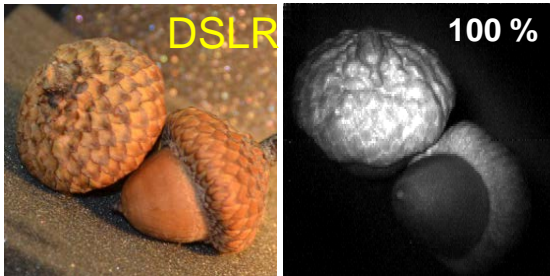
## C: Image collection relevant patterns



## D: Number of blocks ordered patterns

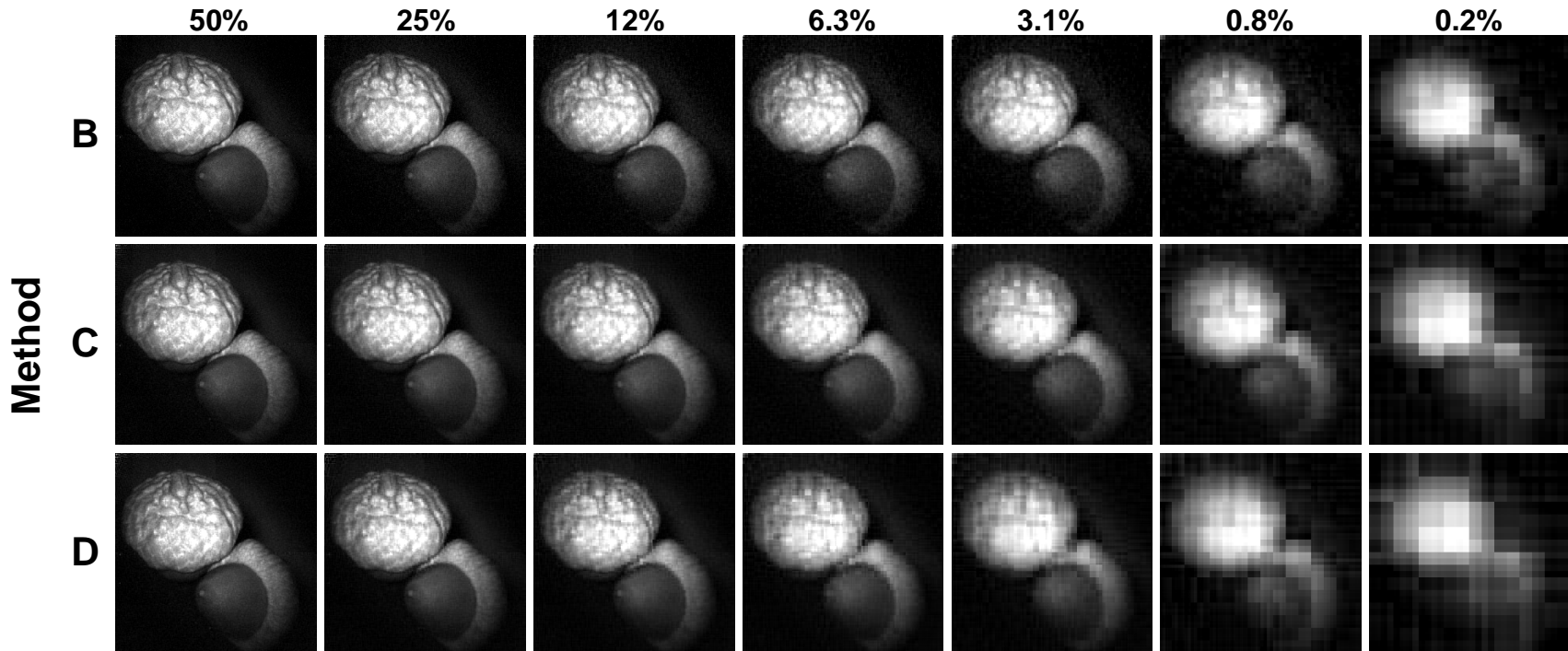


# SWIR images acquired with pulse laser illumination



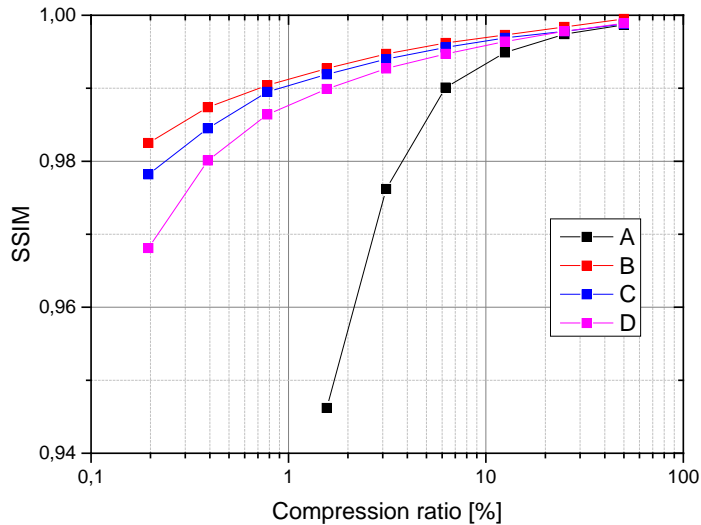
- Reconstructions: 256 x 256 pixels
- Scene adapted pattern selection
- Pulse illumination: 1550 nm, 10 ns, 4  $\mu$ J

CS Ratio: M/N [%]

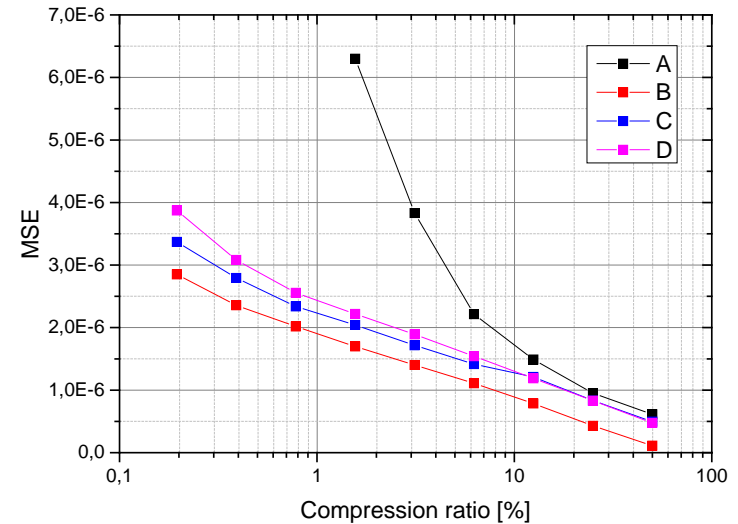


# Image quality metrics

## Structural Similarity Index



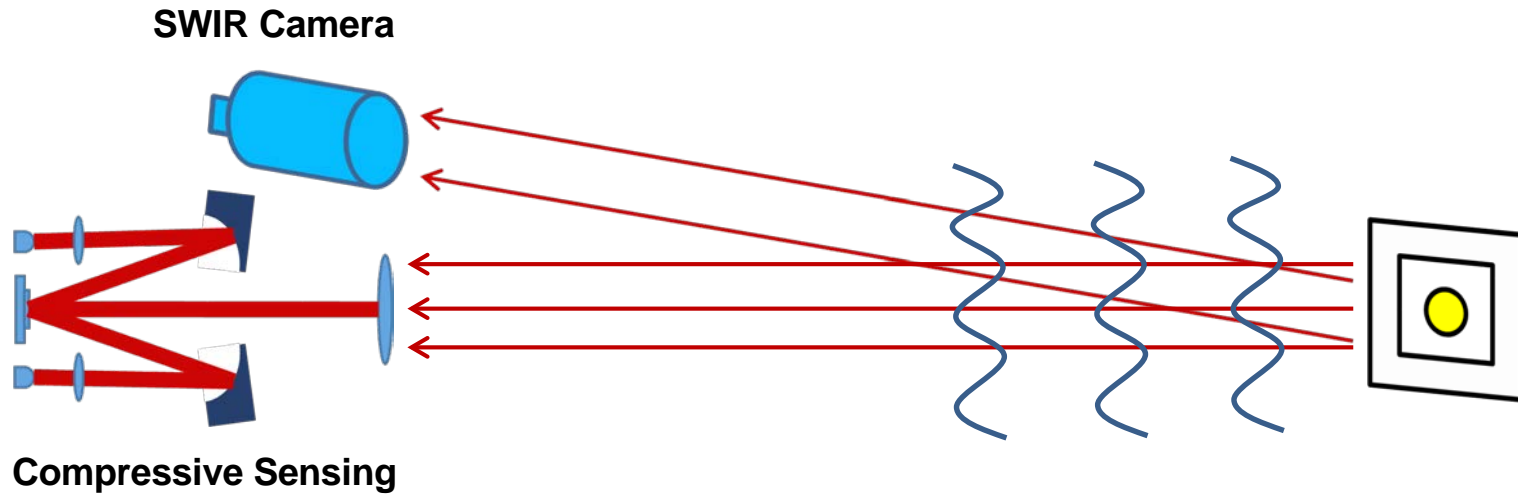
## Mean Square Error



- A: Sequency ordered patterns
- B: Scene adapted pattern selection
- C: Image collection relevant patterns
- D: Number of blocks ordered patterns

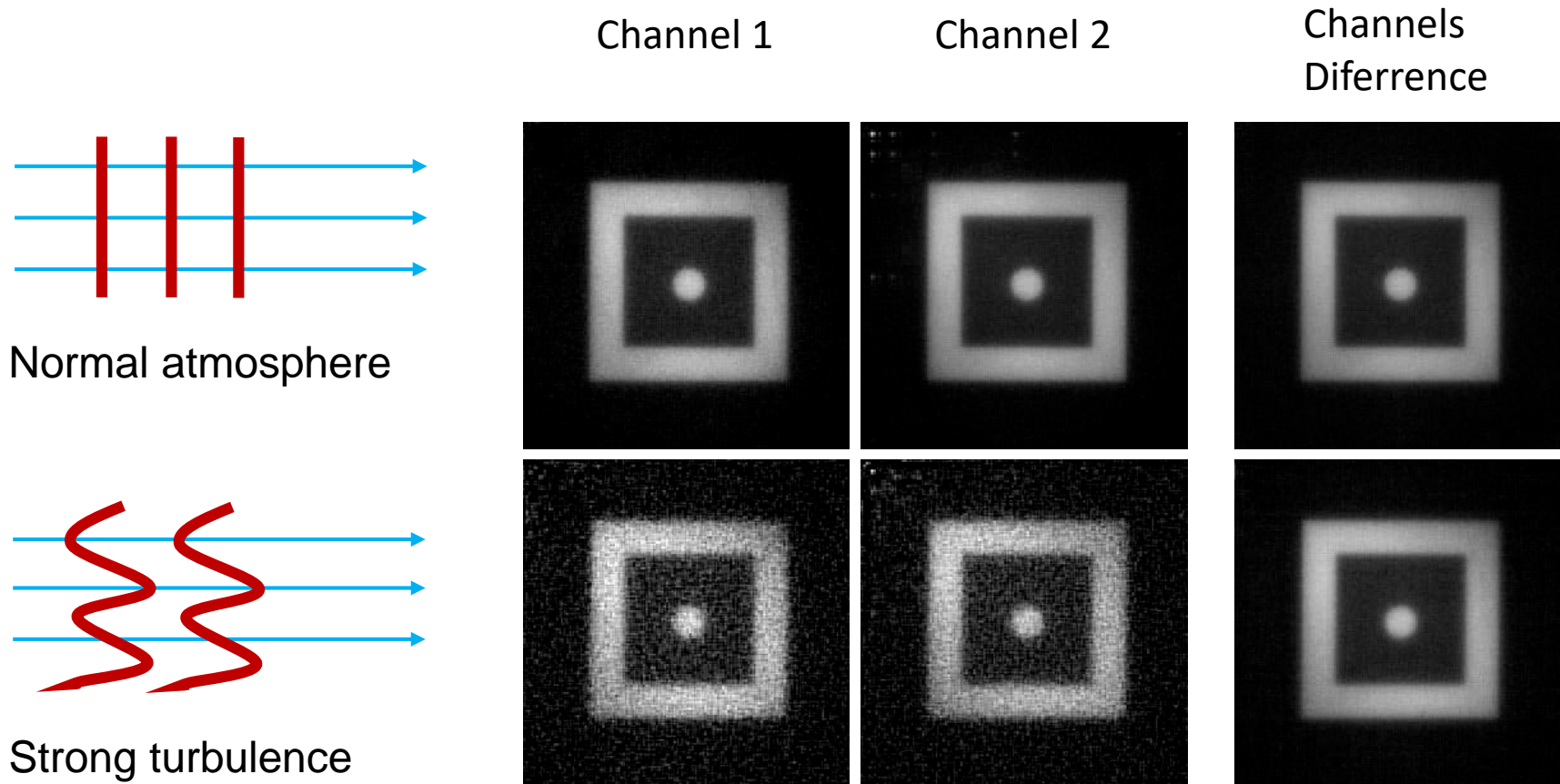


# Experiments through turbulence

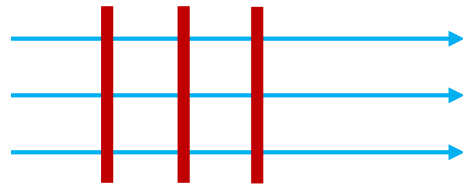


	<b>Compressive Sensing</b>	<b>SWIR Camera</b>
Detector	InGaAs single element (2x)	InGaAs - FPA
Resolution	256 x 256	640 x 512 (256 x 256 used)
Pixel Size	41.1 $\mu\text{m}$ (3 x 3 micromirrors pro pixel)	25 $\mu\text{m}$
Optics	600 mm F/6	400 mm F/4
IFOV	68.5 mrad	62.5 mrad

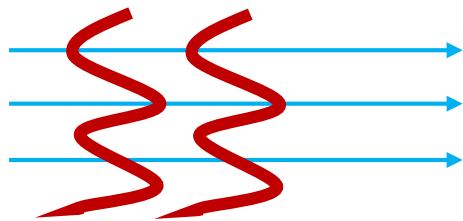
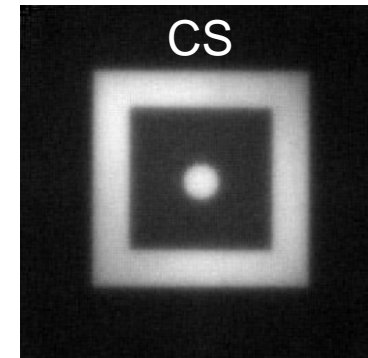
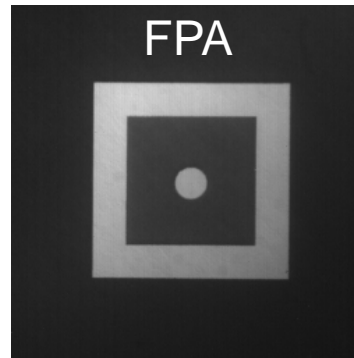
# CS imaging through turbulence



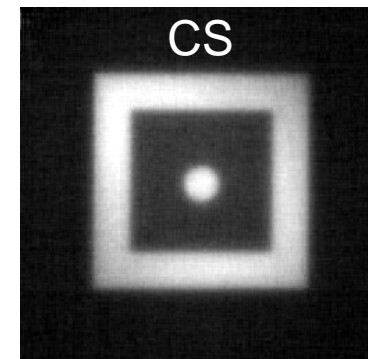
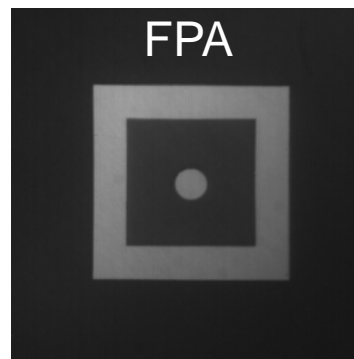
# Comparison FPA – CS under strong turbulence



Normal atmosphere



Strong turbulence



# Data fitting

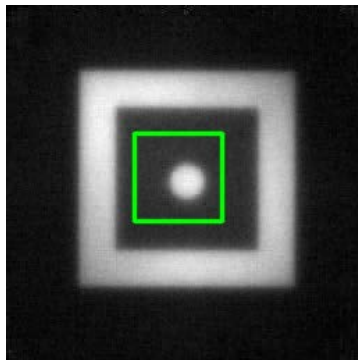
$$I_{circle}(x, y) = c_{background} + c_{circle} \cdot \text{sigmoid} \left( s, \sqrt{(x - x_0)^2 + (y - y_0)^2}, r_0 \right)$$

$r_0$  – radius of the circle

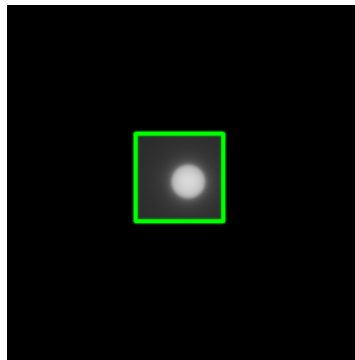
$x_0, y_0$  – center of the circle coordinates

$s$  – sharpness parameter

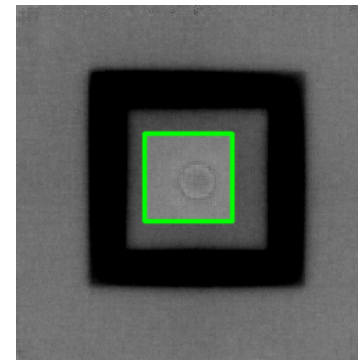
$$\text{Fluctuations} = \text{IFOV} \times \sqrt{\text{std}(x_0)^2 + \text{std}(y_0)^2}$$



$I(x_i, y_i)$

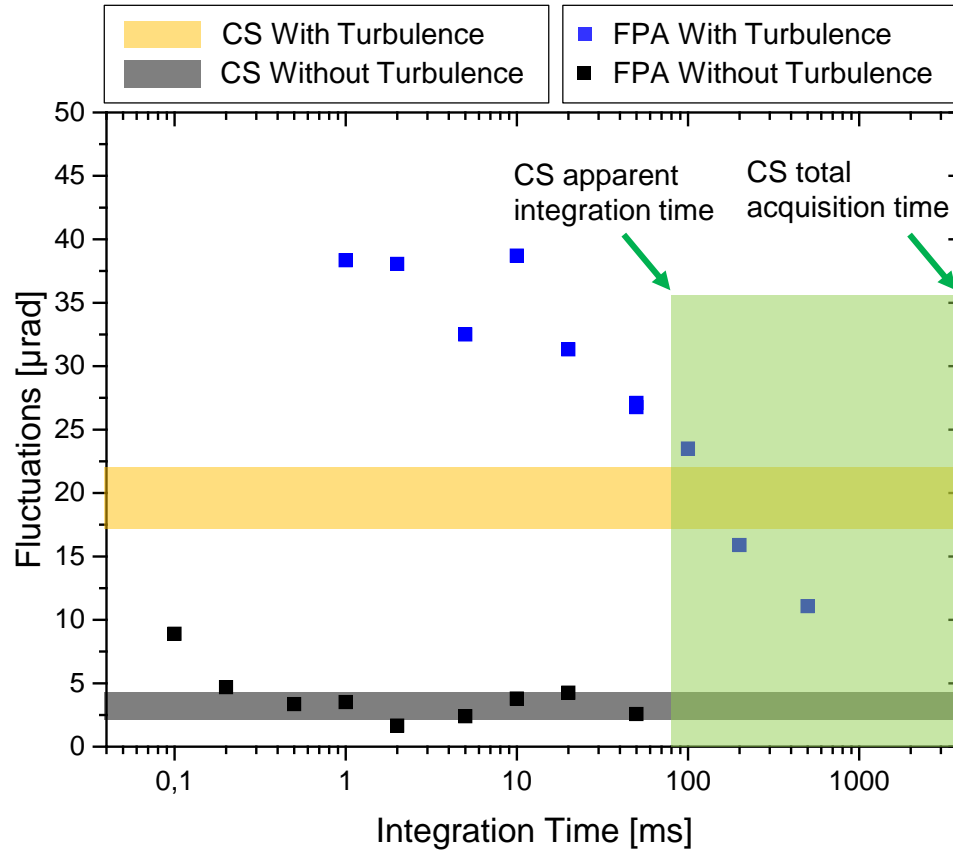


$I_{circle}(x_i, y_i)$



$I(x_i, y_i) - I_{circle}(x_i, y_i)$

# Evaluation of position fluctuations



Apparent integration time:  $\text{Number of patterns} \times \text{Integration time} / \text{pattern}$

Total acquisition time:  $\text{Number of patterns} \times \text{DMD frame rate}$

# Summary

- Compressive sensing measurements have been performed in SWIR and VIS range - non-coherent and coherent illumination (cw and pulse)
- Four different methods have been applied and compared to select the encoding pattern based on Hadamard matrix
- Turbulence influence on a SWIR CS imaging was investigated in comparison to an InGaAs-FPA based camera
- The measurements showed that the CS reconstructed images experience similar turbulence-induced effects like the FPA-based camera
- The experiments performed **so far** could not demonstrate an advantage for one of the two image acquisition concepts